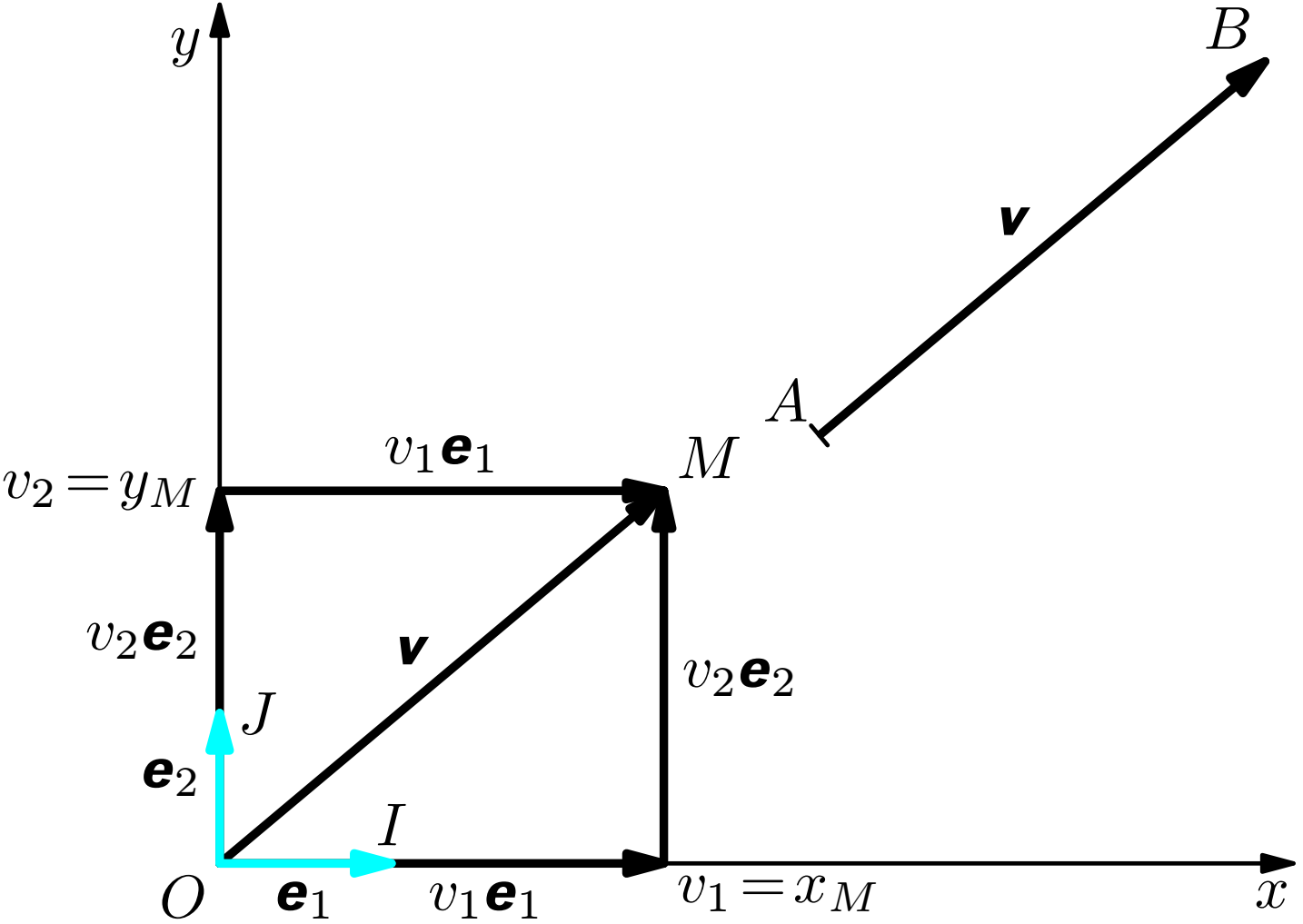
y
B
$\boldsymbol{v}$
A
$v_1\boldsymbol{e}_1$
M
$v_2 = y_M$
$v_2\boldsymbol{e}_2$
$\boldsymbol{v}$
$v_2\boldsymbol{e}_2$
J
$\boldsymbol{e}_2$
I
O
$\boldsymbol{e}_1$
$v_1\boldsymbol{e}_1$
$v_1 = x_M$
x