

Magneto-rotational instability

EP 34
(náč 1)

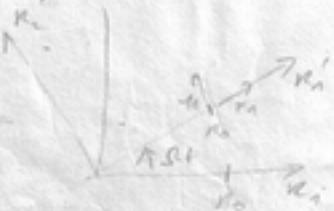
- nejprve mechanické analogie: aké částice v centrálním roli společné pravidlo libovolného K

pd. rovnice: $\frac{d^2x_1}{dt^2} = 2\Omega \frac{dy_1}{dt} - R \frac{d\Omega}{dK} x_1 + \frac{K}{m} (x_2 - x_1) \quad (1)$
v kartézském syst.

$$(x = r' - r_0) \quad \frac{d^2y_1}{dt^2} = -2\Omega \frac{dx_1}{dt} + \frac{K}{m} (y_2 - y_1) \quad (2)$$

$$\frac{d^2x_2}{dt^2} = 2\Omega \frac{dy_2}{dt} - R \frac{d\Omega}{dK} x_2 + \frac{K}{m} (x_1 - x_2) \quad (3)$$

$$\frac{d^2y_2}{dt^2} = -2\Omega \frac{dx_2}{dt} + \frac{K}{m} (y_1 - y_2) \quad (4)$$



Coriolis

$$-K \frac{d\Omega}{dK} x_i = \text{grav. + odstředivý růle} = (\Omega^2 - \Omega_n^2) R$$

$$\Omega = \text{konstanta} = \Omega_n(K)$$

změna polohy $R \rightarrow R_0 = R_n(R_0)$, Ω funkce $\rightarrow \Omega_n(K)$

$$(1) + (3): \frac{d^2}{dt^2}(x_1 + x_2) = 2\Omega \frac{d}{dt}(y_1 + y_2) - R \frac{d\Omega}{dR} (x_1 + x_2)$$

$$(2) + (4): \frac{d^2}{dt^2}(y_1 + y_2) = -2\Omega \frac{d}{dt}(x_1 + x_2)$$

$$\text{res. ve formi } \propto \exp(-i\omega t) \rightarrow \omega^2 = R \frac{d\Omega^2}{dR^2} + 4\Omega^2 \equiv \omega^2$$

$$(1) - (3): \frac{d^2}{dt^2}(x_1 - x_2) = 2\Omega \frac{d}{dt}(y_1 - y_2) - R \frac{d\Omega}{dR} (x_1 - x_2) - \frac{2K}{m} (x_1 - x_2)$$

$$(2) - (4): \frac{d^2}{dt^2}(y_1 - y_2) = -2\Omega \frac{d}{dt}(x_1 - x_2) - \frac{2K}{m} (y_1 - y_2)$$

\rightarrow další řešení:

$$\omega^4 - \left(\frac{4K}{m} + \omega^2 \right) \omega^2 + \frac{2K}{m} \left(\frac{2K}{m} + R \frac{d\Omega^2}{dR^2} \right) = 0$$

- imaginární kořeny pro $\left(\frac{2K}{m} + R \frac{d\Omega^2}{dR^2} \right) < 0 \wedge K > 0$

- prototipe v kružnicích dleci je $\frac{d\Omega}{dR} < 0$, $\frac{d\Omega^2}{dR^2} > 0$

dostatečné faktury amplituda vede k nestabiliti

- prvního náhradního m. pole
- maximální je zjednodušené získat

$$\rightarrow \vec{B} = B_z \hat{e}_z + \vec{B}_\perp, \quad \nabla \cdot \vec{v} = 0, \quad \vec{k} = k \hat{e}_z, \quad \vec{v} = \vec{v}_\perp + \vec{v}_z$$

- nekladíme $\vec{k} = k \hat{e}_z \Rightarrow v_{1z} = 0$
- Maxwell + $k = k \hat{e}_z \Rightarrow B_{1z} = 0$

- ideální NHD \rightarrow zaměření na pole do plazmaty:

$$\frac{\partial \vec{B}}{\partial t} = \nabla \times (\vec{v} \times \vec{B})$$

- v cylindrických souř.

$$\nabla \times \vec{A} = \left(\frac{1}{R} \frac{\partial F_2}{\partial \varphi} - \frac{\partial F_\varphi}{\partial z}, \frac{\partial F_R}{\partial z} - \frac{\partial F_2}{\partial R}, \frac{1}{R} \frac{\partial}{\partial R} (RF_\varphi) - \frac{1}{R} \frac{\partial F_R}{\partial \varphi} \right)$$

$$\oplus \frac{\partial}{\partial \varphi} = 0 \quad \oplus \text{zaměření } O(B_z^2), O(B_z v_\varphi) :$$

$$\frac{\partial B_{1R}}{\partial t} = B_z \frac{\partial v_{1\varphi}}{\partial z} \quad (5)$$

$$\frac{\partial B_{1\varphi}}{\partial t} = R \frac{dL}{dR} B_{1R} + B_z \frac{\partial v_{1\varphi}}{\partial z} \quad (6)$$

- mě tam ve druhé rovině vychází $\frac{\partial v_{1\varphi}}{\partial R}$ neníto $R \frac{dL}{dR}$.

- Eulerov rovina s Lorentzovou sílou $\vec{j}' = \vec{j} \times \vec{B}$

$$\oplus \text{Maxwell: } \nabla \times \vec{B} = \mu_0 \vec{j}$$

$$\rightarrow \frac{\partial v_{1R}}{\partial t} - 2L v_{1\varphi} = \frac{B_z}{\mu_0 \rho} \frac{\partial B_{1R}}{\partial z} \quad (7)$$

$$\frac{\partial v_{1\varphi}}{\partial t} + \frac{2e}{2\pi} v_{1R} = \frac{B_z}{\mu_0 \rho} \frac{\partial B_{1\varphi}}{\partial z} \quad (8)$$

$$0 = - \frac{\partial P_1}{\partial z} - \frac{B_{1R}}{\mu_0 \rho} \frac{\partial B_{1R}}{\partial z} \quad \leftarrow \text{takže nejdříve rotovat}$$

$$\text{pomoc} \propto \exp[i(kz - \omega t)]$$

$$\text{Alfvénova rychlos: } v_A^2 = \frac{B_z^2}{\mu_0 \rho}$$

$$\rightarrow \omega^4 - (2k^2 v_A^2 + \omega^2) \omega^2 + k^2 v_A^2 (k^2 v_A^2 + R \frac{dL^2}{dR^2}) = 0$$

\rightarrow nestabilit

$$-\text{maximální m. pro } \omega = \frac{1}{2} R \left| \frac{dL}{dR} \right|, \quad k v_A = R^2 - \frac{\omega^2}{16 \pi^2}$$

- vložit způsobení m. do mola projevit jenko člen $\propto B_0 B_4 \propto T_{\text{eq}}$
- není mi jasné, jestli by do toho řla transformace provedená v rovnici (8)

ad rovnice (5)-(8):

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$$\nabla \times (\mathbf{v} \times \mathbf{B}) = \mathbf{v} (\nabla \cdot \mathbf{B}) + (\mathbf{B} \cdot \nabla) \mathbf{v} - \mathbf{B} (\nabla \cdot \mathbf{v}) - (\mathbf{v} \cdot \nabla) \mathbf{B}$$

kovariantní:

$$[\nabla \times (\mathbf{v} \times \mathbf{B})]^a = v^a B^b_{;b} + B^b v^a_{;b} - B^a v^b_{;b} - v^b B^a_{;b}$$

$$\text{kde } \mathbf{v}^a = (r, \phi, z) = (v_r, \frac{v_\phi}{r}, v_z)$$

$$g_{ab} = \begin{pmatrix} 1 & r^2 0 \\ 0 & 1 \end{pmatrix} \quad \Gamma^a_{bc} = \frac{1}{2} g^{ad} (g_{cd,b} + g_{bd,c} - g_{bc,d})$$

$$\text{jednotlivé nesúlôvky: } \Gamma^r_{kr} = \Gamma^r_{qr} = \frac{1}{r}, \quad \Gamma^r_{qq} = -r$$

$$B^b_{;b} = 0 \quad (\text{Maxwell}), \quad v^b_{;b} = 0 \quad -\text{nestlačitelnost}$$

$$[\nabla \times (\mathbf{v} \times \mathbf{B})]^r = B^b v^k_{;b} - v^b B^k_{;b} =$$

$$= B^k v^r_{;k} + B^q v^r_{;q} - \cancel{B^r R v^0} + B^2 v^r_{;2} - v^k B^r_{;k} - \cancel{v^q B^r_{;q}} + \cancel{v^0 R B^q} - \cancel{v^2 B^q_{;2}} =$$
$$= B^2 v^r_{;2} + O(B^2)$$

$$[\nabla \times (\mathbf{v} \times \mathbf{B})]^q = \frac{1}{r} [\nabla \times (\mathbf{v} \times \mathbf{B})]_q =$$

$$= B^k v^q_{;k} + B^r v^q_{;q} + B^2 v^q_{;2} - v^k B^q_{;k} - v^r B^q_{;q} - v^2 B^q_{;2} =$$

$$= B^k v^q_{;k} + \frac{1}{r} B^r v^q_{;q} + B^4 v^q_{;4} + \cancel{B^q \frac{1}{r} v^k} + B^2 v^q_{;2} -$$

$$- v^k B^q_{;k} - \frac{1}{r} v^q B^q_{;q} - v^r B^q_{;q} - v^2 B^q_{;2} =$$

$$= B^r \frac{\partial \varphi}{\partial k} + B^2 \frac{\partial \varphi}{\partial z} + O(B^2)$$

zde je den je iere
i jemstva, nesu,
takto by bylo na pravu
znamenat "nesu"
"nesu" vysledku vle

$$\mathbf{v} \cdot \nabla \mathbf{v} = v^a v^b_{;a}$$

$$[\mathbf{v} \cdot \nabla \mathbf{v}]^r = v^k v^k_{;k} + v^q v^q_{;q} - v^r R v^4 + v^2 v^k_{;2} =$$

$$= -(v^q)^2 r + O(v^2) = -\frac{1}{r} v^q = (-R \varphi) - 2 R v_{,q} + O(v^2)$$

$$v^q = 0 \in v_{,q} = 0$$

$$[\mathbf{v} \cdot \nabla \mathbf{v}]^q = v^k v^q_{;k} + \frac{1}{r} v^k v^q_{;q} + v^q v^q_{;q} + \frac{1}{r} v^q v^k_{;k} + v^2 v^q_{;2} =$$

$$= v^k \frac{\partial \varphi}{\partial k} + \frac{2}{r} v^k \varphi = \frac{1}{r} \frac{v^k}{2 \varphi} [2 R \varphi \frac{\partial \varphi}{\partial k} + 4 \varphi^2] = \frac{1}{r} \frac{2 \varphi^2}{2 \varphi} v^k$$

$$= \frac{1}{r} [\mathbf{v} \cdot \nabla \mathbf{v}]_q$$

$$\nabla \times (\mathbf{v} \times \mathbf{B}) = \frac{\partial \mathbf{B}}{\partial t} \quad \vec{k} \cdot \mathbf{k}_z \hat{\mathbf{e}}_z \quad B_{xz} = 0 \quad v_{xz} = 0 \quad \boxed{\text{ord NRI}}$$

$$[\nabla \times (\mathbf{v} \times \mathbf{B})]_x = \frac{1}{R} \frac{\partial}{\partial \varphi} [\mathbf{v} \times \mathbf{B}]_z - \frac{\partial}{\partial z} [\mathbf{v} \times \mathbf{B}]_\varphi =$$

$$= \frac{1}{R} \frac{\partial}{\partial \varphi} [v_r B_\varphi - v_\varphi B_r] - \frac{\partial}{\partial z} [v_{rz} B_\varphi - v_{\varphi z} B_r] \approx B_z \frac{\partial v_{r\varphi}}{\partial z}$$

||
0

↪ LHS La mi brachte
→ dann dividieren noch

$$\frac{\partial B_\varphi}{\partial t} = [\nabla \times (\mathbf{v} \times \mathbf{B})]_\varphi = \frac{\partial}{\partial z} [\mathbf{v} \times \mathbf{B}]_x - \frac{\partial}{\partial R} [\mathbf{v} \times \mathbf{B}]_z = \text{jetzt}$$

$$= \frac{\partial}{\partial z} (v_r B_z - v_z B_r) - \frac{\partial}{\partial R} (v_{rz} B_r - v_r B_z)$$

mehrere b. v. r. ??

$$\frac{\partial B_\varphi}{\partial t} \sim B_z \frac{\partial v_r}{\partial z} + B_r R \frac{\partial v_z}{\partial R}$$

$$J_{\text{current}} = \mathbf{j} \times \mathbf{B} = \frac{1}{\mu_0} (\nabla \times \mathbf{B}) \times \mathbf{B}$$

$$J_R = \frac{1}{\mu_0} [\nabla \times \mathbf{B}]_\varphi \times \mathbf{B}_z - \frac{1}{\mu_0} [\nabla \times \mathbf{B}]_z \times \mathbf{B}_\varphi =$$

$$= \frac{1}{\mu_0} \left(\frac{\partial B_n}{\partial z} - \frac{\partial B_z}{\partial n} \right) B_z - \frac{1}{\mu_0} \left(\frac{1}{R} \frac{\partial}{\partial n} (RB_\varphi) - \frac{1}{R} \frac{\partial B_\varphi}{\partial n} \right) B_\varphi$$

$$\approx \frac{1}{\mu_0} B_z \frac{\partial B_n}{\partial z} + O(B_z^2)$$

$$J_\varphi = \frac{1}{\mu_0} [\nabla \times \mathbf{B}]_z B_R - \frac{1}{\mu_0} [\nabla \times \mathbf{B}]_R B_z = \frac{1}{\mu_0} \left(\frac{1}{R} \frac{\partial}{\partial n} (RB_\varphi) - \frac{1}{R} \frac{\partial B_\varphi}{\partial n} \right) B_R$$

$$- \frac{1}{\mu_0} \left(\frac{1}{R} \frac{\partial B_z}{\partial n} - \frac{\partial B_n}{\partial z} \right) B_z \approx \frac{1}{\mu_0} B_z \frac{\partial B_\varphi}{\partial z} + O(B_z^2)$$

$$J_z = \frac{1}{\mu_0} [\nabla \times \mathbf{B}]_R B_\varphi - \frac{1}{\mu_0} [\nabla \times \mathbf{B}]_\varphi B_R = \frac{1}{\mu_0} \left(\frac{1}{R} \frac{\partial B_\varphi}{\partial n} - \frac{\partial B_n}{\partial z} \right) B_\varphi -$$

$$- \frac{1}{\mu_0} \left[\frac{\partial B_n}{\partial z} - \frac{\partial B_z}{\partial n} \right] B_R \approx - \frac{1}{\mu_0} B_\varphi \frac{\partial B_n}{\partial z} + O(A_1^2)$$

$$\nabla \times \mathbf{F} = \left(\frac{1}{R} \frac{\partial F_2}{\partial z} - \frac{\partial F_0}{\partial z}, \frac{\partial F_R}{\partial z} - \frac{\partial F_2}{\partial R}, \frac{1}{R} \frac{\partial}{\partial R} (RF_\varphi) - \frac{1}{R} \frac{\partial F_\varphi}{\partial R} \right)$$

R

φ

z

$$-\omega^2(x_1+x_2) = -2i\omega R(y_1+y_2) - R \frac{d\ell^2}{dR}(x_1+x_2)$$

$$-\omega^2(y_1+y_2) = 2i\omega R(x_1+x_2)$$

$$(R \frac{d\ell^2}{dR} - \omega^2)(x_1+x_2) + 2i\omega R(y_1+y_2) = 0$$

$$-2i\omega R(x_1+x_2) - \omega^2(y_1+y_2) = 0$$

$$\omega^2(R \frac{d\ell^2}{dR} - \omega^2) + 4\omega^2 R^2 = 0$$

$$\omega^2 = R \frac{d\ell^2}{dR} + 4\ell^2 = 2e^2$$